

# Magnetic confinement and the solar tachocline

Toby Wood

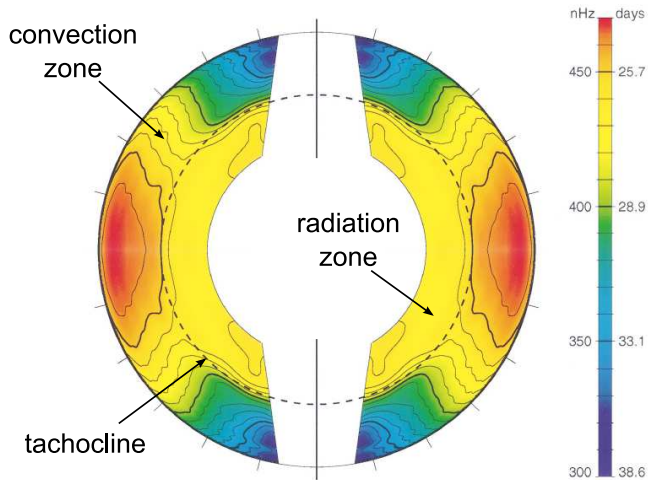
Applied Mathematics and Statistics,  
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In collaboration with Pascale Garaud,  
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# Outline

- 1 The Sun's meridional flows and magnetic field
- 2 Does the Sun have a tilted magnetic field?

# The solar rotation



Schou et al. 1998

## The solar tachocline

E. A. Spiegel<sup>1</sup> and J.-P. Zahn<sup>1,2</sup>

<sup>1</sup> Astronomy Department, Columbia University, New York, NY 10027, USA

<sup>2</sup> Observatoire Midi-Pyrénées, 14 avenue E. Belin, F-31400 Toulouse, France

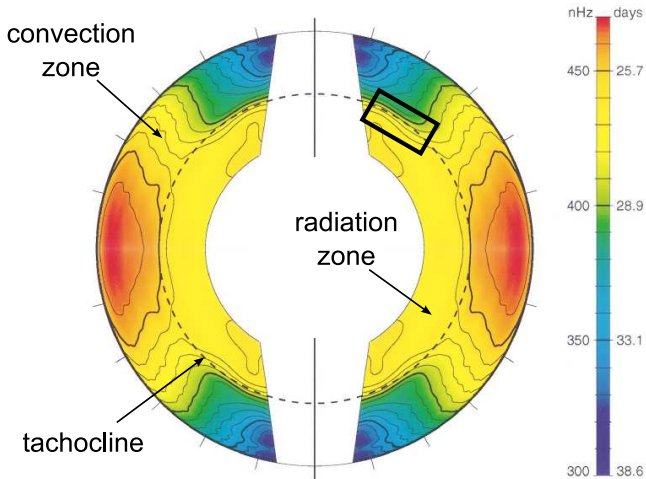
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<sup>1</sup> When the existence of such a layer was first adumbrated, the term *tachycline* was proposed (Spiegel 1972). Here we defer to the terminological sensibilities of D.O. Gough and modify that neologism.

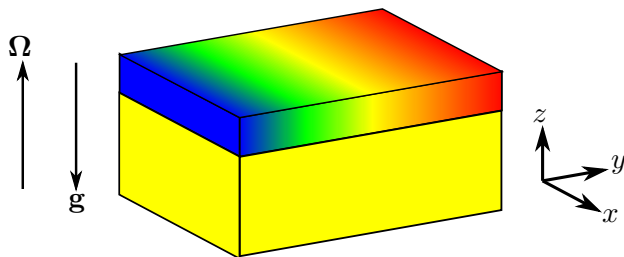
Words matter.

# The solar rotation



Schou et al. 1998

# Hydrodynamic burrowing



Consider linear, Boussinesq perturbations within stably stratified interior.

$$\frac{\partial \mathbf{u}}{\partial t} + 2\Omega \mathbf{e}_z \times \mathbf{u} = -\nabla \hat{p} + \hat{T} \mathbf{e}_z$$

$$\nabla \cdot \mathbf{u} = 0$$

$$\frac{\partial \hat{T}}{\partial t} + N^2 u_z = \kappa \nabla^2 \hat{T}$$

# Hydrodynamic burrowing

$$\frac{\partial u_x}{\partial t} - 2\Omega u_y = 0$$

$$\frac{\partial u_y}{\partial t} + 2\Omega u_x = -\frac{\partial \hat{p}}{\partial y}$$

$$\frac{\partial u_z}{\partial t} = -\frac{\partial \hat{p}}{\partial z} + \hat{T}$$

$$\frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z} = 0$$

$$\frac{\partial \hat{T}}{\partial t} + N^2 u_z = \kappa \nabla^2 \hat{T}$$

# Hydrodynamic burrowing

$$\frac{\partial u_x}{\partial t} - 2\Omega u_y = 0$$

$$\cancel{\frac{\partial u_y}{\partial t}} + 2\Omega u_x = -\frac{\partial \hat{p}}{\partial y} \quad \text{cyclotrophic balance}$$

$$\cancel{\frac{\partial u_z}{\partial t}} = -\frac{\partial \hat{p}}{\partial z} + \hat{T} \quad \text{hydrostatic balance}$$

$$\frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z} = 0$$

$$\cancel{\frac{\partial \hat{T}}{\partial t}} + N^2 u_z = \kappa \nabla^2 \hat{T} \quad \text{local thermal equilibrium}$$



# Hydrodynamic burrowing

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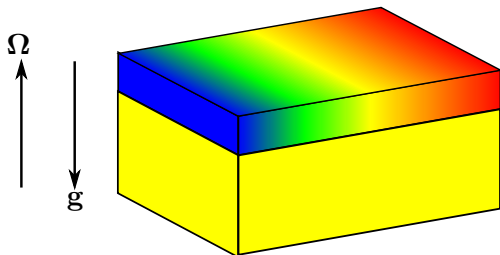
$$\cancel{\frac{\partial \hat{T}}{\partial t}} + N^2 u_z = \kappa \nabla^2 \hat{T} \quad \text{local thermal equilibrium}$$

$$\text{If } \left| \frac{\partial^2}{\partial y^2} \right| = \frac{1}{L^2} \ll \left| \frac{\partial^2}{\partial z^2} \right| \text{ then}$$

$$\frac{\partial u_x}{\partial t} = -\frac{L^4}{t_{\text{ES}}} \frac{\partial^4 u_x}{\partial z^4}$$

$$\text{where } t_{\text{ES}} = \frac{N^2}{4\Omega^2} \frac{L^2}{\kappa}$$

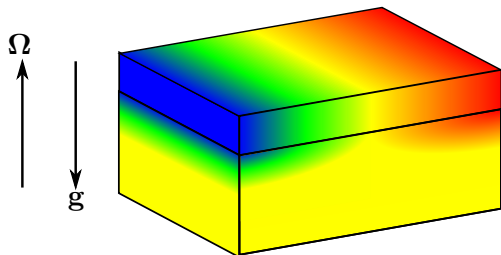
# Hydrodynamic burrowing



$$\frac{\partial u_x}{\partial t} = -\frac{L^4}{t_{\text{ES}}} \frac{\partial^4 u_x}{\partial z^4}$$

A 3D coordinate system with axes labeled  $x$ ,  $y$ , and  $z$ . The  $z$ -axis is vertical, the  $x$ -axis is horizontal to the right, and the  $y$ -axis is diagonal to the right.

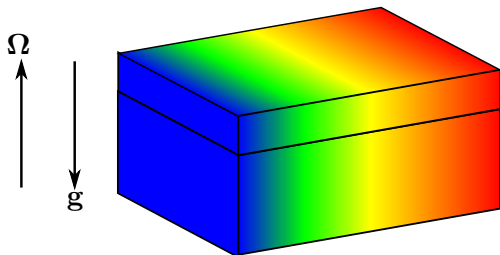
# Hydrodynamic burrowing



$$\frac{\partial u_x}{\partial t} = -\frac{L^4}{t_{\text{ES}}} \frac{\partial^4 u_x}{\partial z^4}$$

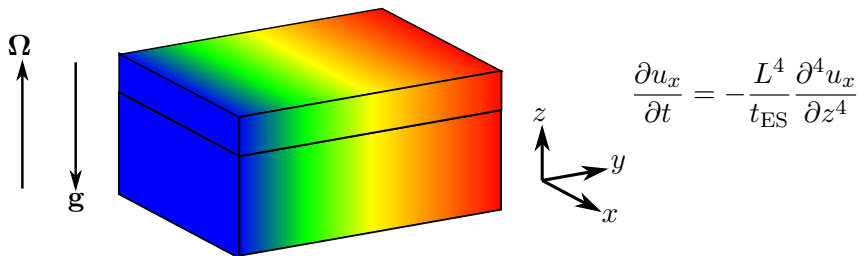
A 3D coordinate system with axes labeled  $x$ ,  $y$ , and  $z$ . The  $z$ -axis is vertical, the  $x$ -axis is horizontal to the right, and the  $y$ -axis is diagonal towards the bottom right.

# Hydrodynamic burrowing



$$\frac{\partial u_x}{\partial t} = -\frac{L^4}{t_{\text{ES}}} \frac{\partial^4 u_x}{\partial z^4}$$

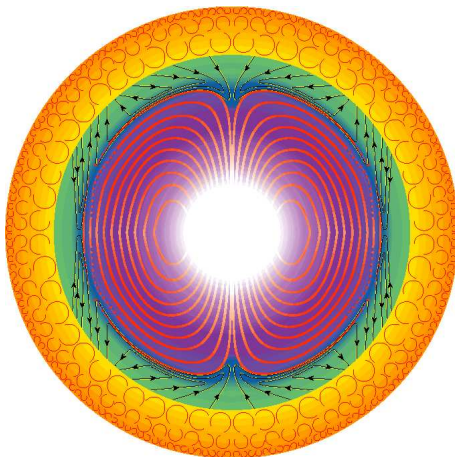
# Hydrodynamic burrowing



- Angular momentum transported by meridional flows (not viscous diffusion)
- Adding viscosity inhibits the burrowing of meridional flows, but *enhances* the spread of differential rotation

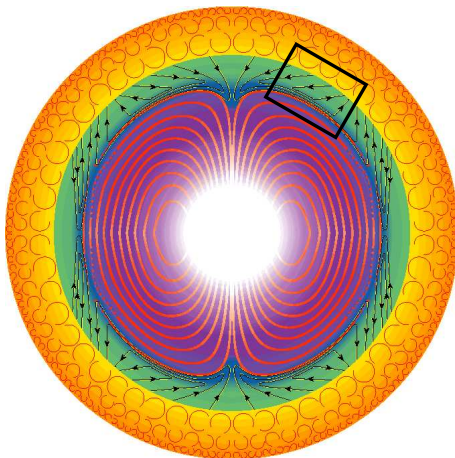
What stops the burrowing?

# The interior magnetic field



Gough & McIntyre 1998

# The interior magnetic field

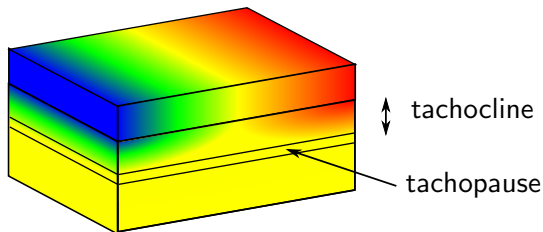


Gough & McIntyre 1998

# The Gough & McIntyre model

Add a uniform, horizontal magnetic field into the background.

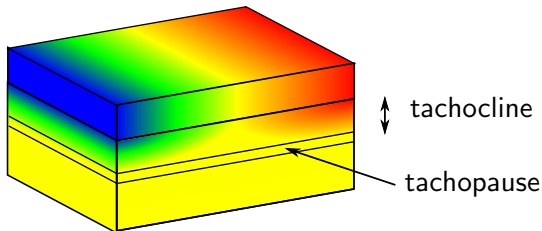
Can now find steady boundary-layer solutions of the linear equations.





# The Gough & McIntyre model

Add a uniform, horizontal magnetic field into the background.  
Can now find steady boundary-layer solutions of the linear equations.



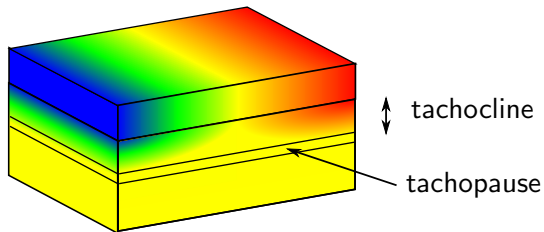
Assume tachocline is (mean) field free.

Estimate  $u_z$  from thermal-wind balance and local thermal equilibrium.

Can add “non-linear flavour” by equating tachopause thickness to  $\eta/|u_z|$ .

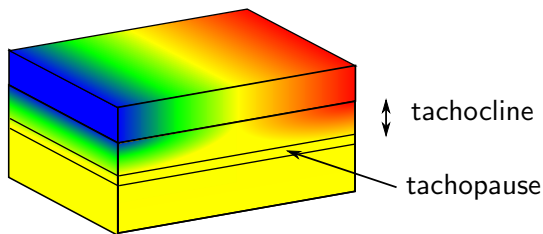
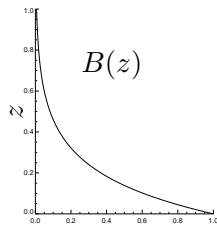
# Wood, McCaslin & Garaud 2011

Can we couple the tachocline to the tachopause?  
(and to the convection zone and radiation zone?)



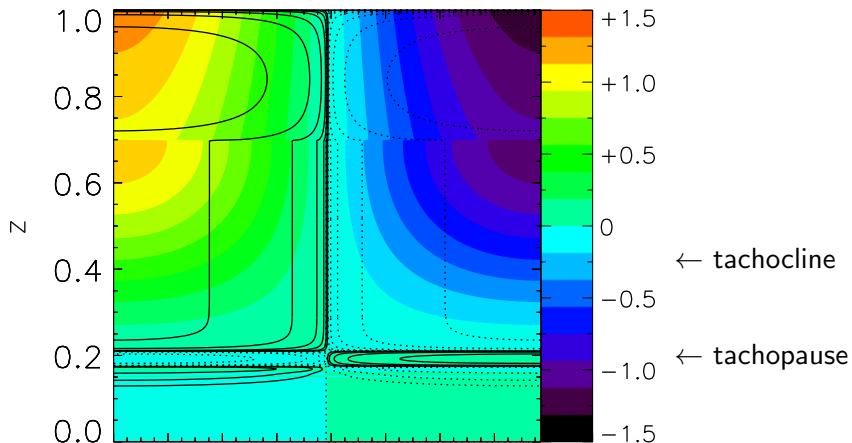
# Wood, McCaslin & Garaud 2011

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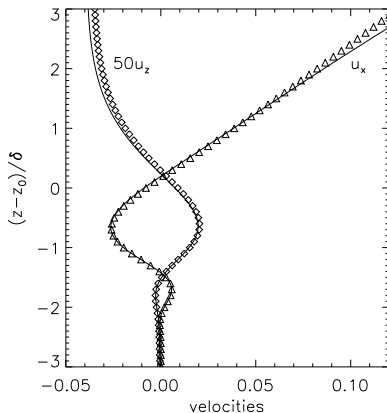
Incorporate uniform downwelling  $U$  and confined field  $B$  into background.  
Add forcing term and turbulent thermal diffusivity in convection zone.

Where does tachopause form? Does  $u_z$  follow GM98 scaling?



# Wood, McCaslin & Garaud 2011

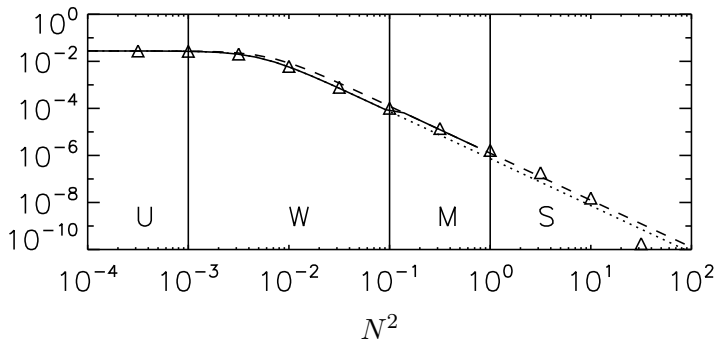
- Tachopause thickness  $\delta \sim \eta/U$
- Tachopause forms where  $B^2 \sim \Omega \eta (L/\delta)^2$



# Wood, McCaslin & Garaud 2011

- Within the tachocline,

$$u_z \sim \frac{\bar{u}_{cz}}{G_{cz} + G_{tp} + G_{tc} \Omega t_{ES}}$$

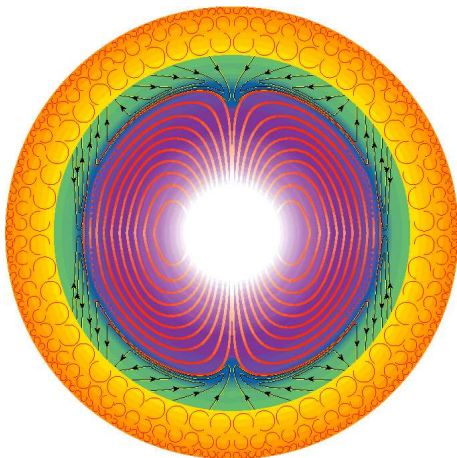


- With realistic parameters, recover GM98 scaling for meridional flow
- But tachopause structure quite different  
⇒ different prediction for  $|B|$
- Lessons for numerical models

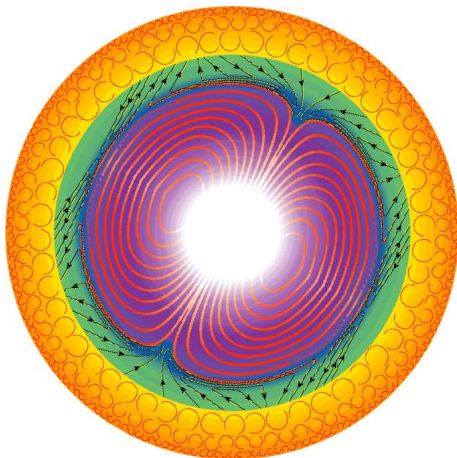




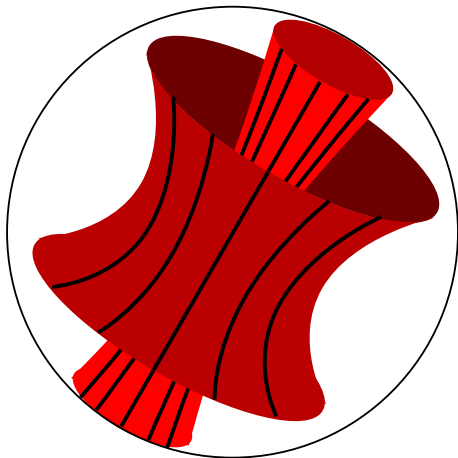
# Why an axial dipole?



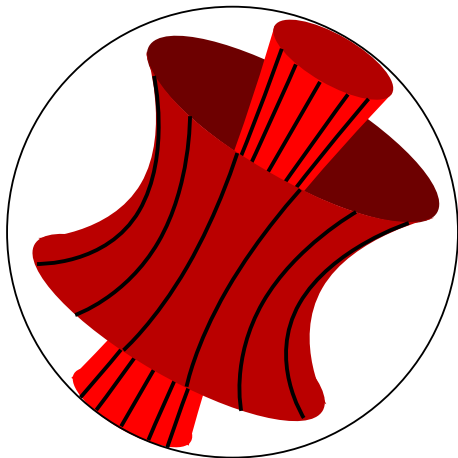
# Why an axial dipole?



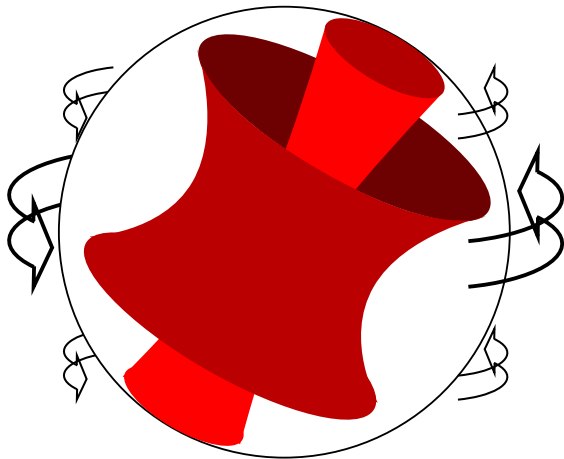
## A tilted magnetic field



## A tilted magnetic field



## A tilted magnetic field



# A tilted magnetic field

What happens to the dipole axis?

# A tilted magnetic field

What happens to the dipole axis?

- 1 The dipole aligns with the rotation axis
- 2 The dipole aligns with the equator
- 3 Nothing

# A tilted magnetic field

What happens to the dipole axis?

- 1 The dipole aligns with the rotation axis
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Angular momentum conservation will tell us!



# A tilted magnetic field

$$\mathbf{v}(\mathbf{r}, t) = \boldsymbol{\Omega}(\psi, t) \times \mathbf{r}$$

where

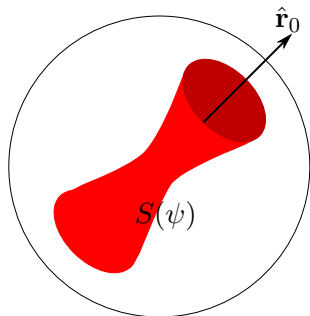
$$\boldsymbol{\Omega}(\psi, t) = \omega(\psi, t) \hat{\mathbf{r}}_0(t) + \boldsymbol{\Omega}'(t)$$

and

$$\boldsymbol{\Omega}' \cdot \hat{\mathbf{r}}_0 = 0.$$

Then

$$\frac{d\hat{\mathbf{r}}_0}{dt} = \boldsymbol{\Omega} \times \hat{\mathbf{r}}_0 = \boldsymbol{\Omega}' \times \hat{\mathbf{r}}_0.$$



# A tilted magnetic field

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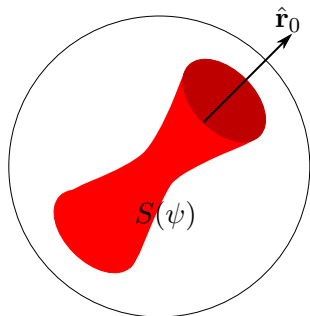
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Then

$$\frac{d\hat{\mathbf{r}}_0}{dt} = \boldsymbol{\Omega} \times \hat{\mathbf{r}}_0 = \boldsymbol{\Omega}' \times \hat{\mathbf{r}}_0.$$

Suppose that  $\mathbf{f} = \lambda(\mathbf{v}_{\text{tc}} - \mathbf{v})$ , where

$$\mathbf{v}_{\text{tc}}(\mathbf{r}) = \Omega_{\text{tc}}(\theta) \mathbf{e}_z \times \mathbf{r}.$$



## A tilted magnetic field

$$\frac{d\hat{\mathbf{r}}_0}{dt} = \boldsymbol{\Omega}' \times \hat{\mathbf{r}}_0$$

$$\hat{\mathbf{r}}_0 \times \frac{d\boldsymbol{\Omega}'}{dt} = \frac{8\pi\lambda}{3I} \hat{\mathbf{r}}_0 \times [\bar{\Omega}_{\text{tc}} \mathbf{e}_z - \boldsymbol{\Omega}'] - \langle \omega \rangle_I \boldsymbol{\Omega}'$$

$$\frac{\partial \omega}{\partial t} = \dots$$

where  $\bar{\Omega}_{\text{tc}} = \frac{\int_{\text{sph.}} \Omega_{\text{tc}} \sin^2 \theta \, dS}{\int_{\text{sph.}} \sin^2 \theta \, dS}$  and  $\langle \omega \rangle_I = \frac{\int_{\psi} \omega \, dI}{\int_{\psi} dI}$

## A tilted magnetic field

$$\frac{d\hat{\mathbf{r}}_0}{dt} = \mathbf{\Omega}' \times \hat{\mathbf{r}}_0$$

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Steady states require that  $\langle \omega \rangle_I \hat{\mathbf{r}}_0 + \mathbf{\Omega}' = \bar{\Omega}_{\text{tc}} \mathbf{e}_z$ .

## An example

Suppose the sphere has constant density, a uniform magnetic field, and no internal friction.

Suppose also that  $\Omega_{tc}(\theta) = a + b \cos^2 \theta$ .

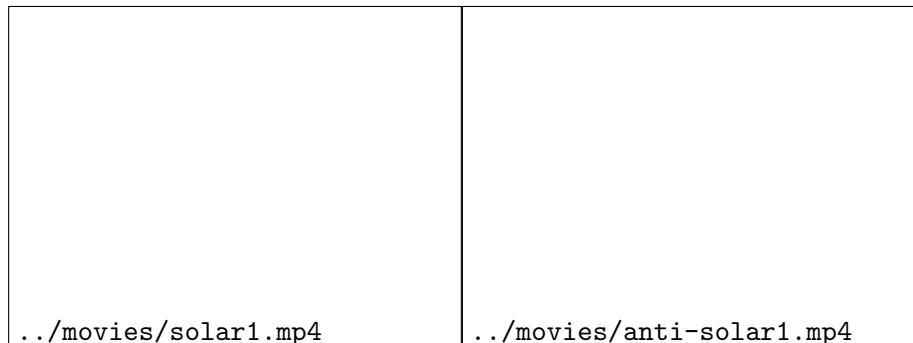
`../movies/solar1.mp4`

`../movies/anti-solar1.mp4`

## An example

Suppose the sphere has constant density, a uniform magnetic field, and no internal friction.

Suppose also that  $\Omega_{tc}(\theta) = a + b \cos^2 \theta$ .



There is a tilted steady state with  $\cos \theta_0 = \pm \sqrt{3/5} \Rightarrow \theta_0 \approx 39^\circ$ .

# Stability of the axial dipole

We have

$$\frac{d\hat{\mathbf{r}}_0}{dt} = \mathbf{\Omega}' \times \hat{\mathbf{r}}_0$$

$$\hat{\mathbf{r}}_0 \times \frac{d\mathbf{\Omega}'}{dt} = \frac{8\pi\lambda}{3I} \hat{\mathbf{r}}_0 \times [\bar{\Omega}_{tc} \mathbf{e}_z - \mathbf{\Omega}'] - \langle \omega \rangle_I \mathbf{\Omega}'$$

$$\frac{\partial \omega}{\partial t} = \dots$$

Suppose that

$$\hat{\mathbf{r}}_0 = \mathbf{e}_z + \delta\hat{\mathbf{r}}_0$$

$$\mathbf{\Omega}' = 0 + \delta\mathbf{\Omega}'$$

$$\omega = \Omega + \delta\omega$$

Then

$$\frac{d}{dt} \delta\hat{\mathbf{r}}_0 = \delta\mathbf{\Omega}' \times \mathbf{e}_z$$

$$\mathbf{e}_z \times \frac{d}{dt} \delta\mathbf{\Omega}' = -\frac{8\pi\lambda}{3I} \mathbf{e}_z \times [\bar{\Omega}_{tc} \delta\hat{\mathbf{r}}_0 + \delta\mathbf{\Omega}'] - \langle \Omega \rangle_I \delta\mathbf{\Omega}'$$

# Stability of the axial dipole

Growth rates  $\sigma$  are found by solving

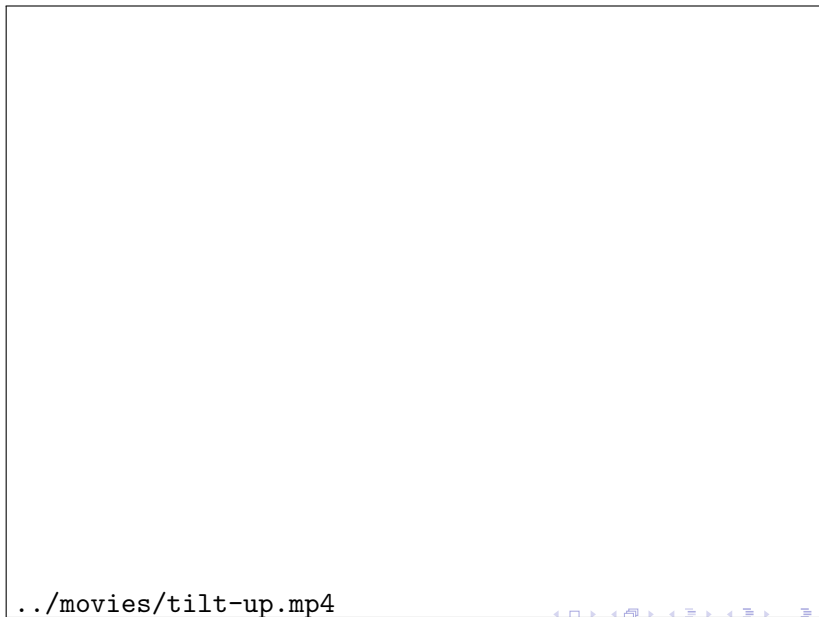
$$0 = \sigma^2 \left( \sigma + \frac{8\pi\lambda}{3I} \right)^2 + \left( \sigma \langle \Omega \rangle_I + \frac{8\pi\lambda}{3I} \bar{\Omega}_{tc} \right)^2.$$

Hence the aligned dipole is stable if and only if

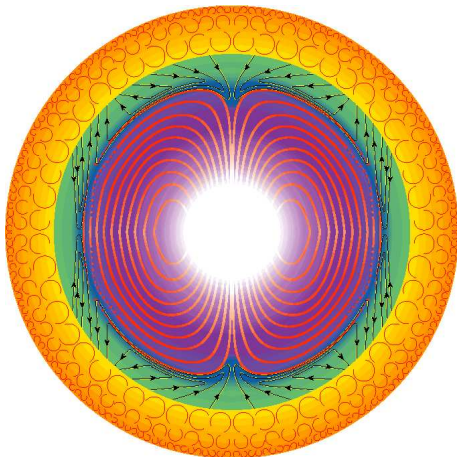
$$\frac{\langle \Omega \rangle_I}{\bar{\Omega}_{tc}} > 1.$$



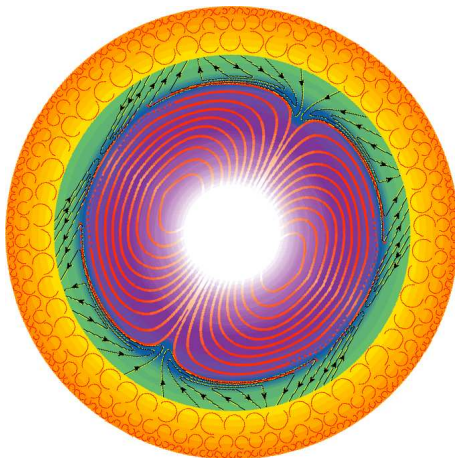
# Stability of the axial dipole



# The solution?



# The solution?



# The solution?



Thank you!



## The tachopause solution

$$\hat{u}_z = ik\delta u_t \left[ I_1(\zeta) - \frac{\pi}{2} \operatorname{Re} \left\{ \exp \left( -\frac{1+i}{\sqrt{2}} \zeta \right) \right\} \right] \\ + \frac{1}{2} k^2 \delta^2 T_t \left[ I_2(\zeta) - \frac{\pi}{2} \operatorname{Re} \left\{ (\gamma - i\frac{\pi}{4}) \exp \left( -\frac{1+i}{\sqrt{2}} \zeta \right) \right\} \right]$$

where  $\gamma$  is the Euler–Mascheroni constant,  $\gamma = 0.577\dots$ ,  
 $\zeta = \exp((z_0 - z)/\delta)$ , and

$$I_1(\zeta) = \int_0^\infty \frac{s \, ds}{e^{\zeta s}} \frac{1}{1 + s^4},$$
$$I_2(\zeta) = \int_0^\infty \frac{s \, ds}{e^{\zeta s}} \frac{\gamma + \ln s}{1 + s^4}.$$

## Meridional flow in the tachocline

$$w_t = \frac{-i\bar{u}_{cz}}{\frac{kd}{2\tau_c} \coth\left(\frac{1-h}{d}\right) + \frac{4}{\pi k\delta} + \frac{n_{rz}^2}{2k^2 E_\kappa} [G_1 + G_2 - G_3]}$$

where

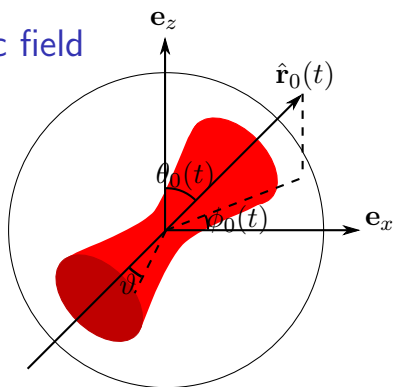
$$G_1 = kD - \frac{f_0[2 - 2\operatorname{sech} kD + \tanh kz_0 \tanh kD] + \tanh k(1-h) \tanh kD}{f_0[\tanh kz_0 + \tanh kD] + \tanh k(1-h)[\tanh kz_0 \tanh kD + 1]}$$

$$G_2 = \frac{kd}{k^2 d^2 - 1} \left[ kd - \frac{\tanh k(1-h)}{\tanh\left(\frac{1-h}{d}\right)} \right] \frac{1 - \operatorname{sech} kh \cosh kz_0}{f_0 \tanh kh + \tanh k(1-h)}$$

$$G_3 = \gamma k\delta \frac{f_0[1 - \operatorname{sech} kD] \tanh kz_0 + \tanh k(1-h) \tanh kD \tanh kz_0}{f_0[\tanh kz_0 + \tanh kD] + \tanh k(1-h)[\tanh kz_0 \tanh kD + 1]}$$



## A tilted magnetic field



$$\frac{dI}{d\psi} \frac{\partial \omega}{\partial t} = \frac{\partial}{\partial \psi} \left( \mu \frac{\partial \omega}{\partial \psi} \right) + \frac{dA}{d\psi} \lambda \sin^2 \vartheta \left( \left[ \Omega_{cz}(\theta) \frac{\partial \cos \theta}{\partial \cos \vartheta} \right]_{C(\psi)} - \omega \right)$$